Introduction to Statistical Machine Learning with Applications in Econometrics Lecture 9: Recap of OLS

Instructor: Ma, Jun

Renmin University of China

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Linear causal model

- Suppose we have a random sample $\{(Y_i, X_i^{\top}) : i = 1, 2, ..., n\}$, where $X_i = (X_{i,1}, X_{i,2}, ..., X_{i,k})$ with k < n. $X_{i,j}$: the *j*-th variable for the *i*-th observation. By convention, $X_{i,1} = 1$. Its coefficient corresponds to the intercept.
- ► Assume the data is i.i.d.: (Y_i, X_i^{\top}) has the same distribution as (Y_j, X_j^{\top}) and is independent of (Y_j, X_j^{\top}) , $\forall i \neq j$.
- Linear model: Y = X^Tβ + U. X: observed explanatory variables; U: unobserved explanatory factor.
- (Y_i, X_i^{\top}) is generated by the model: $Y_i = X_i^{\top} \beta + U_i$ for some U_i .
- Strong exogeneity: E[U | X] = 0 (implies E[U] = 0).
- Weak exogeneity: E[U] = E[UX] (= Cov[U, X]) = 0.
- OLS estimator of β :

$$\widehat{\beta} = \underset{b_1,...,b_p}{\operatorname{argmin}} \sum_{i=1}^n \left(Y_i - b_1 X_{i,1} - b_2 X_{i,2} - \dots - b_p X_{i,k} \right)^2.$$

- We should give an interpretation of the linear part X^T_iβ as a feature of the population (the distribution of (Y, X^T)).
- Under strong exogeneity, $E[Y | X] = X^{\top}\beta$.
- Under weak exogeneity, $X^{\top}\beta$ is the best linear approximation of $E[Y \mid X]: \beta = (E[XX^{\top}])^{-1}E[XY]$ and

$$\beta = \operatorname*{argmin}_{b \in \mathbb{R}^k} \mathbb{E}\left[\left(\mathbb{E}\left[Y \mid X \right] - X^\top b \right)^2 \right].$$

 β is called projection coefficients.

- Homoskedastic model: $E[U^2 | X] = \sigma^2 > 0.$
- Heteroskedastic model: $E[U^2 | X]$ is a function of X.

Matrix notations

• We can stack these *n* equations together

$$Y_1 = X_1^{\top}\beta + U_1$$

$$Y_2 = X_2^{\top}\beta + U_2$$

$$\vdots \vdots \vdots$$

$$Y_n = X_n^{\top}\beta + U_n.$$

► Define

$$\mathbf{Y} = \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix}, \ \mathbf{X} = \begin{pmatrix} X_1^\top \\ X_2^\top \\ \vdots \\ X_3^\top \end{pmatrix}, \ \mathbf{U} = \begin{pmatrix} U_1 \\ U_2 \\ \vdots \\ U_n \end{pmatrix}$$

Y and **U** are $n \times 1$ vectors and **X** is an $n \times k$ matrix. The (i, j) element of **X** is the *i*-th observation on the *j*-th regressor.

- The system of *n* equations can be written as $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{U}$.
- No multicollinearity: rank $(\mathbf{X}) = k$.

► For a homoskedastic model,

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{U}$$
$$\mathbf{E} [\mathbf{U} | \mathbf{X}] = \mathbf{0}$$
$$\operatorname{Var} [\mathbf{U} | \mathbf{X}] = \sigma^{2}\mathbf{I}_{n},$$

where I_n denotes the *n*-dimensional identity matrix.

OLS in matrix notations

- The OLS estimator of β is obtained by solving $\widehat{\beta} = \operatorname{argmin}_{b \in \mathbb{R}^k} \|\mathbf{Y} \mathbf{X}b\|.$
- Then, $\widehat{\beta} = (\mathbf{X}^{\top}\mathbf{X})^{-1}\mathbf{X}^{\top}\mathbf{Y}$ and the fitted residuals are $\widehat{\mathbf{U}} = \mathbf{Y} \mathbf{X}\widehat{\beta}$.
- $\widehat{\mathbf{U}}$ satisfies $\mathbf{X}^{\top}\widehat{\mathbf{U}} = \mathbf{0}$.
- The OLS is unbiased: $E\left[\widehat{\beta} \mid \mathbf{X}\right] = \beta$.
- Under homoskedasticity, $\operatorname{Var}\left[\widehat{\beta} \mid \mathbf{X}\right] = \sigma^2 (\mathbf{X}^{\mathsf{T}} \mathbf{X})^{-1}$.

Projection matrices

- ► Let **X** be $n \times k$ with rank (**X**) = k. Then define $P_{\mathbf{X}} = \mathbf{X} (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top}$. $P_{\mathbf{X}} \mathbf{Y} = \mathbf{X} (\mathbf{X}^{\top} \mathbf{X})^{-1} \mathbf{X}^{\top} \mathbf{Y} = \mathbf{X} \widehat{\beta}$ gives the fitted values.
- ► The fitted residuals are

$$\widehat{\mathbf{U}} = \mathbf{Y} - \mathbf{X}\widehat{\beta} = \mathbf{Y} - \mathbf{X} \left(\mathbf{X}^{\top}\mathbf{X}\right)^{-1} \mathbf{X}^{\top}\mathbf{Y} = \left(\mathbf{I}_n - \mathbf{X} \left(\mathbf{X}^{\top}\mathbf{X}\right)^{-1} \mathbf{X}^{\top}\right) \mathbf{Y}.$$

- ► We define $M_X = \mathbf{I}_n \mathbf{X} (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top = \mathbf{I}_n P_X$. $M_X \mathbf{Y}$ gives the fitted residuals.
- Properties of P_X and M_X :
 - P_X and M_X are symmetric;
 - $P_X X = X$ and $M_X X = 0$;
 - P_X and M_X are orthogonal: $M_X P_X = 0$ and $P_X M_X = 0$;
 - P_X and M_X are idempotent: $P_X P_X = P_X$ and $M_X M_X = M_X$;
 - ► rank $(\mathbf{P}_{\mathbf{X}}) = k$ and rank $(\mathbf{M}_{\mathbf{X}}) = n k$.

Partitioned regression

• Partition $\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 & \mathbf{X}_2 \end{bmatrix}, \boldsymbol{\beta} = (\boldsymbol{\beta}_1^{\mathsf{T}}, \boldsymbol{\beta}_2^{\mathsf{T}})^{\mathsf{T}}$ and the model as

$$\mathbf{Y} = \mathbf{X}_1 \boldsymbol{\beta}_1 + \mathbf{X}_2 \boldsymbol{\beta}_2 + \mathbf{U},$$

where \mathbf{X}_1 is $n \times k_1$ and \mathbf{X}_2 is $n \times k_2$ $(k_1 + k_2 = k)$.

• Partition
$$\widehat{\beta} = \left(\widehat{\beta}_1^{\mathsf{T}}, \widehat{\beta}_2^{\mathsf{T}}\right)^{\mathsf{T}}$$

• Denote $M_1 = M_{X_1}$ and $M_2 = M_{X_2}$. Then,

$$\widehat{\beta}_1 = (\mathbf{X}_1^{\top} \boldsymbol{M}_2 \mathbf{X}_1)^{-1} (\mathbf{X}_1^{\top} \boldsymbol{M}_2 \mathbf{Y})$$
$$\widehat{\beta}_2 = (\mathbf{X}_2^{\top} \boldsymbol{M}_1 \mathbf{X}_2)^{-1} (\mathbf{X}_2^{\top} \boldsymbol{M}_1 \mathbf{Y})$$

and

$$\operatorname{Var}\left[\widehat{\beta}_{1} \mid \mathbf{X}\right] = \sigma^{2} \left(\mathbf{X}_{1}^{\top} \boldsymbol{M}_{2} \mathbf{X}_{1}\right)^{-1}$$
$$\operatorname{Var}\left[\widehat{\beta}_{2} \mid \mathbf{X}\right] = \sigma^{2} \left(\mathbf{X}_{2}^{\top} \boldsymbol{M}_{1} \mathbf{X}_{2}\right)^{-1}$$

Omitted variable bias

- Suppose the researcher estimates β_1 by regressing **Y** on **X**₁ only. Let $\tilde{\beta}_1 = (\mathbf{X}_1^{\top} \mathbf{X}_1)^{-1} (\mathbf{X}_1^{\top} \mathbf{Y})$ denote the OLS estimates.
- ► Then,

►

$$\widetilde{\beta}_{1} = (\mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{1})^{-1} (\mathbf{X}_{1}^{\mathsf{T}}\mathbf{Y})$$

$$= \beta_{1} + (\mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{1})^{-1} \mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{2}\beta_{2} + (\mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{1})^{-1} \mathbf{X}_{1}^{\mathsf{T}}\mathbf{U}$$
and E $\left[\widetilde{\beta}_{1} \mid \mathbf{X}\right] = \beta_{1} + (\mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{1})^{-1} \mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{2}\beta_{2}.$
 $(\mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{1})^{-1} \mathbf{X}_{1}^{\mathsf{T}}\mathbf{X}_{2}\beta_{2}$ is the omitted variable bias.

Effects of covariates

- ► In practical applications, we often have a long list of potential explanatory variables. It is possible that *k* is close to *n*.
- Cross-country growth regression estimates the effect of initial GDP on future growth rates, with more than 50 other explanatory variable including institutional and technological factors and a sample of less than 100 observations.
- In addition, to capture the nonlinear effects and interaction effects, we may expand the linear model by incorporating higher order polynomials and interaction terms.
- While only few of the potential covariates may have non-zero coefficients in the true model, unfortunately we do not know which ones.
- Covariates with zero coefficients are called irrelevant.
- To avoid the omitted variables bias, the researcher may attempt to include all potential covariates. Unfortunately, that results in large variances and standard errors on the main parameters of interest.

Partition the regression model:

$$\mathbf{Y} = \beta_1 \mathbf{X}_1 + \mathbf{X}_2 \beta_2 + \mathbf{U},$$

where \mathbf{X}_1 is an $n \times 1$ vector which contains the observations on the main explanatory variable for research.

- X_2 is an $n \times (k 1)$ matrix which includes observations on k 1 other potential explanatory variables (control variables).
- ► The variance of the OLS estimator:

$$\operatorname{Var}\left[\widehat{\beta}_{1} \mid \mathbf{X}\right] = \frac{\sigma^{2}}{\mathbf{X}_{1}^{\mathsf{T}} \boldsymbol{M}_{2} \mathbf{X}_{1}}.$$

• Since $\mathbf{X}_1^{\mathsf{T}} \boldsymbol{M}_2 \mathbf{X}_1 = \mathbf{X}_1^{\mathsf{T}} \boldsymbol{M}_2^{\mathsf{T}} \boldsymbol{M}_2 \mathbf{X}_1 = \widetilde{\mathbf{X}}_1^{\mathsf{T}} \widetilde{\mathbf{X}}_1$, where

$$\widetilde{\mathbf{X}}_1 = \boldsymbol{M}_2 \mathbf{X}_1 = \mathbf{X}_1 - \mathbf{X}_2 \left(\mathbf{X}_2^{\mathsf{T}} \mathbf{X}_2 \right)^{-1} \mathbf{X}_2^{\mathsf{T}} \mathbf{X}_1 = \mathbf{X}_1 - \mathbf{X}_2 \widehat{\boldsymbol{\gamma}}.$$

- $\hat{\gamma}$ is the OLS coefficient from the regression of X_1 against X_2 .
- ➤ X
 ¹ is the vector of OLS residuals from OLS regression of X¹ against X² and X
 ⁺₁X
 ⁺₁ is the sum of the squared residuals.
- ► When we include more control variables, a bigger portion of X₁ is removed resulting in a smaller sum of the squared residuals.
- When we include irrelevant control variables, the variance of the OLS estimator increases. One would see larger standard errors, smaller *t*-statistics, larger *p*-values and wider confidence intervals.
- Two wrong practices: (1) include only significant regressors; (2) data snooping/p-hacking.

Include only significant regressors?

► If a subset of the coefficients in the linear model

$$Y_i = \beta_1 X_{i,1} + \ldots + \beta_k X_{i,k} + U_i$$

are exactly zero, we wish to find the smallest sub-model consisting of only explanatory variables with non-zero coefficients.

- ► Estimate the full model with all variables. Let $T_j = \hat{\beta}_j / SE\left(\hat{\beta}_j\right)$ denote the *t*-statistic for $H_0: \beta_j = 0$ versus $H_1: \beta_j \neq 0$.
- What if we run a second regression with only statistically significant coefficients in the first stage?
- Such a practice would typically result in exclusion of relevant covariates and the omitted variables bias.
 - Hypothesis testing controls for the probability of Type I error but leaves the probability of Type II error uncontrolled.
 - You find a coefficient to be non-significant, possibly due to a high probability of Type II error.
 - Failure to reject H₀: β_j = 0 cannot be used as a reliable evidence that the true coefficient is zero.

Data snooping

- Data snooping or *p*-hacking occurs when the researcher uses the same data in order to produce statistically significant estimates with large *t*-statistics or small *p*-values.
- Data snooping destroys the validity of *t*-statistics and *p*-values and makes the empirical results less convincing.
- You may try dropping different combinations of potential explanatory variables from the regression to get a statistically significant estimate for the main variable of interest.
- Suppose that the researcher can construct *J* independent estimators for θ such that $\hat{\theta}_j \sim N\left(\theta, \sigma_j^2\right)$, j = 1, 2, ..., J, where σ_j^2 is known.
- The researcher conducts J tests with significance level 5% of H₀: θ = 0 against H₁: θ ≠ 0.

- The researcher concludes that $\theta \neq 0$ if one of the *J* tests rejects $\theta = 0$.
- Suppose that in fact $\theta = 0$. The probability of concluding that $\theta \neq 0$ (known as false discovery) is given by

$$\Pr\left[\max_{1 \le j \le J} \left| \frac{\widehat{\theta}_j}{\sigma_j} \right| > 1.96\right] = 1 - \Pr\left[\max_{1 \le j \le J} \left| \frac{\widehat{\theta}_j}{\sigma_j} \right| \le 1.96\right]$$
$$= 1 - \prod_{i=1}^J \Pr\left[\left| \frac{\widehat{\theta}_j}{\sigma_j} \right| \le 1.96 \right]$$
$$= 1 - (0.95)^J.$$

- The false discovery probability quickly grows as J↑∞. E.g., 1 - (0.95)¹⁰ ≈ 40%.
- When the researcher performs many of tests, the Type I error probability is not controlled and may be much larger than the nominal significance level.

- In practice, estimators are rarely independent, the same relationship holds qualitatively.
- ► If the researcher searchers long enough, with a high probability they would find a significant estimate.
- A procedure that automatically detects the smallest sub-model consisting of only relevant explanatory variables guards against data snooping and makes the empirical results more convincing to readers.

One classical approach to model selection

• Order $T_1, ..., T_k$ in absolute value:

$$|T_{(1)}| \ge |T_{(2)}| \ge \cdots \ge |T_{(k)}|.$$

- ► Let \hat{j} denote the value of *j* that minimizes $RSS(j) + js^2\log(n)$, where RSS(j) is the residual sum of squares from the model with *j* variables corresponding to the *j* largest absolute *t*-statistics and $s^2 = (n - k)^{-1} \sum_{i=1}^{n} \widehat{U}_i^2$.
- The selected model is the model with \hat{j} variables corresponding to the \hat{j} largest absolute *t*-statistics.
- ▶ When *n* is large, with high probability, this selected model is the same as the smallest sub-model with only nonzero coefficients.
- ► Disadvantages:
 - Assume homoskedasticity;
 - Break down in high-dimensional regression k > n ($s^2 = 0$).

Convergence in probability

- ► Let {X_n : n = 1, 2, ...} be a sequence of random variables. Let X be random or non-random.
- We will consider non-random sequences with the following typical elements: 1. $E[|X_n X|^r]$; 2. $Pr[|X_n X| > \varepsilon]$ for some $\varepsilon > 0$.
 - Convergence in *r*-th mean. X_n converges to X in *r*-th mean if $E[|X_n X|^r] \rightarrow 0$ as $n \rightarrow \infty$.
 - Convergence in probability. X_n converges in probability to X if for all $\varepsilon > 0$, Pr $[|X_n - X| \ge \varepsilon] \to 0$ as $n \to \infty$. It is denoted as $X_n \to_p X$. If $X_n \to_p 0$, we denote $X_n = o_p(1)$.

- Convergence in *r*-th mean implies convergence in probability.
- (Markov's Inequality) Let *X* be a random variable. For $\varepsilon > 0$ and r > 0,

$$\Pr\left[|X| \ge \varepsilon\right] \le \frac{\mathrm{E}\left[|X|'\right]}{\varepsilon^r}$$

Suppose that X_n converges to X in r-th mean, E $[|X_n - X|^r] \rightarrow 0$. Then,

$$\Pr\left[|X_n - X| \ge \varepsilon\right] \le \frac{\operatorname{E}\left[|X_n - X|^r\right]}{\varepsilon^r} \to 0.$$

- ► Let $X_1, ..., X_n$ be a sample of i.i.d. random variables such that $E[|X_1|] < \infty$. Then, $n^{-1} \sum_{i=1}^n X_i \to_p E[X_1]$ as $n \to \infty$.
- Due to i.i.d. assumption, we have that $E[X_i] = E[X_1]$ for all i = 1, ..., n.

Suppose that $X_n \rightarrow_p a$ and $Y_n \rightarrow_p b$, where *a* and *b* are some finite constants. Let *c* be another constant.

- ► $cX_n \rightarrow_p ca$.
- $\blacktriangleright X_n + Y_n \to_p a + b.$

•
$$X_n Y_n \to_p ab.$$

- $X_n/Y_n \rightarrow_p a/b$, provided that $b \neq 0$.
- If $0 \le X_n \le Y_n$ and $Y_n \to_p 0$, then $X_n \to_p 0$.
- $X_n \rightarrow_p 0$ if and only if $|X_n| \rightarrow_p 0$.

Continuous mapping theorem (CMT)

- Suppose that $X_n \to_p c$, a constant, and let $h(\cdot)$ be a continuous function at *c*. Then, $h(X_n) \to_p h(c)$.
- suppose that $\widehat{\beta}_n \to_p \beta$. Then $\widehat{\beta}_n^2 \to_p \beta^2$, and $1/\widehat{\beta}_n \to_p 1/\beta$, provided $\beta \neq 0$.

Convergence of random vectors

- The random vectors/matrices converge in probability if their elements converge in probability.
- ► Consider the vector case. Let $\{X_n : n = 1, 2, ...\}$ be a sequence of random *k*-vectors. $X_n X \rightarrow_p 0$ element-by-element, where *X* is a possibly random *k*-vector, if and only if $||X_n X|| \rightarrow_p 0$, where $|| \cdot ||$ denotes the Euclidean norm.
- The rules for manipulation of probability limits in the vector/matrix case are similar to those in the scalar case.
- The CMT is valid in vector/matrix case as well.
- OLS estimator is a consistent estimator of the coefficients: $\hat{\beta} \rightarrow_p \beta$.

Convergence in distribution

- Let $\{X_n : n = 1, 2, ...\}$ be a sequence of random variables.
- ► Let $F_n(x)$ denote the marginal CDF of X_n , i.e. $F_n(x) = \Pr(X_n \le x)$. Let F(x) be another CDF.
- We say that X_n converges in distribution if $F_n(x) \to F(x)$ for all x where F(x) is continuous.
- ▶ In this case, we write $X_n \rightarrow_d X$, where X is any random variable with the distribution function F(x).
- ▶ Note that while we say that *X_n* converges to *X*, the convergence in distribution is not convergence of random variables, but of the distribution functions.

- ► The extension to the vector case is straightforward. Let *X_n* and *X* be two random *k*-vectors.
- We say that $X_n \rightarrow_d X$ if the joint CDF of X_n converges to that of X at all continuity points, i.e.

$$F_n(x_1, \dots, x_k) = \Pr \left[X_{n,1} \le x_1, \dots, X_{n,k} \le x_k \right]$$

$$\rightarrow \Pr \left[X_1 \le x_1, \dots, X_k \le x_k \right]$$

$$= F(x_1, \dots, x_k),$$

for all points (x_1, \ldots, x_k) where *F* is continuous.

► In this case, we say that the elements of $X_n, X_{n,1}, \ldots, X_{n,k}$, jointly converge in distribution to X_1, \ldots, X_k , the elements of X.

Rules of convergence in distribution

- (Cramer Convergence Theorem) Suppose that $X_n \rightarrow_d X$ and $Y_n \rightarrow_p c$. Then,
 - $\blacktriangleright X_n + Y_n \to_d X + c.$

$$\blacktriangleright Y_n X_n \to_d c X.$$

- $X_n/Y_n \rightarrow_d X/c$, provided that $c \neq 0$.
- ▶ If $X_n \to_p X$, then $X_n \to_d X$. Converse is not true with one exception: If $X_n \to_d c$, a constant, then $X_n \to_p c$.
- If $X_n Y_n \rightarrow_p 0$, and $Y_n \rightarrow_d Y$, then $X_n \rightarrow_d Y$.

Continuous mapping theorem

- Suppose that $X_n \to_d X$, and let $h(\cdot)$ be a function continuous on a set X such that $\Pr[X \in X] = 1$. Then, $h(X_n) \to_d h(X)$.
- ▶ Note that contrary to convergence in probability, $X_n \rightarrow_d X$ and $Y_n \rightarrow_d Y$ does not imply that, for example, $X_n + Y_n \rightarrow_d X + Y$, unless a joint convergence result holds.

The central limit theorem

- ► Let $X_1, ..., X_n$ be a sample of iid random variables such that $E[X_1] = 0$ and $0 < E[X_1^2] < \infty$. Then, as $n \to \infty$, $n^{-1/2} \sum_{i=1}^n X_i \to_d N(0, E[X_1^2])$.
- Let X_1, \ldots, X_n be a sample of iid random variables with $E[X_1] = \mu$ and $Var[X_1] = \sigma^2 < \infty$. Define

$$\overline{X}_n = n^{-1} \sum_{i=1}^n X_i.$$

• Consider $n^{-1/2} \sum_{i=1}^{n} (X_i - \mu)$. We have that $(X_1 - \mu), \dots, (X_n - \mu)$ are i.i.d. with the mean $E[(X_1 - \mu)] = 0$, and the variance $E[(X_1 - \mu)^2] = \sigma^2 < \infty$. Therefore, by the CLT,

$$n^{1/2} \left(\overline{X}_n - \mu \right) = n^{-1/2} \sum_{i=1}^n \left(X_i - \mu \right)$$
$$\rightarrow_d \quad \mathcal{N} \left(0, \sigma^2 \right).$$

- Let X_n be a random k-vector. Then, $X_n \to_d X$ if and only if $\lambda^\top X_n \to_d \lambda^\top X$ for all non-zero $\lambda \in \mathbb{R}^k$.
- ► Let $X_1, ..., X_n$ be a sample of i.i.d. random *k*-vectors such that $E[X_1] = 0$ (denote $X_i = (X_{i,1}, ..., X_{i,k})^{\top}$) and $E[X_{1,j}^2] < \infty$ for all j = 1, ..., k, and $E[X_1X_1^{\top}]$ is positive definite. Then, $n^{-1/2} \sum_{i=1}^n X_i \rightarrow_d N(0, E[X_1X_1^{\top}]).$

Asymptotic normality of OLS

• Denote $\mathbf{V} = \mathbf{E} \left[U_i^2 X_i X_i^{\mathsf{T}} \right]$ and $\mathbf{G} = \mathbf{E} \left[X_i X_i^{\mathsf{T}} \right]$. Then,

$$\sqrt{n}\left(\widehat{\beta}-\beta\right) = \left(\frac{1}{n}\sum_{i=1}^{n}X_{i}X_{i}^{\top}\right)^{-1}\left(\frac{1}{\sqrt{n}}\sum_{i=1}^{n}X_{i}U_{i}\right)$$

and $n^{-1} \sum_{i=1}^{n} X_i X_i^{\top} \rightarrow_p \mathbf{G}$ and $n^{-1/2} \sum_{i=1}^{n} X_i U_i \rightarrow_d \mathbf{N}(\mathbf{0}, \mathbf{V})$. \blacktriangleright Then,

$$\sqrt{n}\left(\widehat{\beta}-\beta\right) \rightarrow_{d} \mathrm{N}\left(\mathbf{0},\mathbf{G}^{-1}\mathbf{V}\mathbf{G}^{-1}\right).$$

• In the homoskedastic model, $\mathbf{V} = \sigma^2 \mathbf{G}$ and $\mathbf{G}^{-1} \mathbf{V} \mathbf{G}^{-1} = \sigma^2 \mathbf{G}^{-1}$.

Bounded in probability

- ► Suppose that $\lambda_n = \sqrt{n} \left(\widehat{\theta} \theta \right) \rightarrow_d N(0, \sigma^2)$. We say that the sequence $\{\lambda_n\}_{n=1}^{\infty}$ is bounded in probability and denote $\lambda_n = O_p(1)$.
- Suppose that $\xi_n \rightarrow_p 0$ ($\xi_n = o_p(1)$). Then, $\xi_n \lambda_n = o_p(1) O_p(1) = o_p(1)$.
- ► We also write

$$\widehat{\theta} = \theta + \frac{1}{\sqrt{n}} \cdot \lambda_n = \theta + \frac{1}{\sqrt{n}} \cdot O_p(1) = \theta + O_p\left(\frac{1}{\sqrt{n}}\right).$$

 $\widehat{\theta}$ converges to θ at the rate $n^{-1/2}$.

• More generally, we write $X_n = O_p(\alpha_n)$ for some non-random sequence α_n , if $X_n/\alpha_n = O_p(1)$.